

Semantics of machine operations

- To be able to check formally that operations work as they supposed to, we have to assign precise mathematical meaning (semantics) to them
- Operations in general are concerned with changing the local state and setting output variables
- A specification of an operation basically describes the relationship between initial (before) and final (after) states



Machine states

- Machine states include the combinations of all possible values of (input, output, local) machine variables
- Machine states can be modelled as values of cartesian product on machine variable types, for example, $NAT \times NAT$ for two variables of natural numbers
- An operation is then state transformation described using Abstract Machine Notation



Different kinds of state transformation

- Functional (deterministic) execution — one-to-one relationship between initial and final states
- Non-deterministic execution — one-to-many relationship
- Aborting execution — one-to-zero relationship
- Infeasible execution — execution is in “waiting mode” or “hybernation”



Weakest preconditions

- We are often interested only in certain “expected” or “acceptable” final states
- A predicate P describing a set of “acceptable” final states is called a *postcondition*
- $[S]P$ denotes all initial states from which execution of S is guaranteed to achieve P . $[S]P$ – *weakest precondition*
- The B Method provides rules for calculating weakest preconditions for different statements



Weakest precondition rules for some B Statements

$[x := e] P$	\equiv	$P[e/x]$
$[x,y := e1,e2] P$	\equiv	$P[e1,e2/x,y]$
$[\text{skip}] P$	\equiv	P
$[\text{PRE } E \text{ THEN } S \text{ END}] P$	\equiv	$E \wedge [S]P$
$[\text{IF } E \text{ THEN } S1 \text{ ELSE } S2 \text{ END}] P$	\equiv	$(E \Rightarrow [S1]P) \wedge$ $(\neg E \Rightarrow [S2]P)$
$[\text{CASE } E \text{ OF}$		
$\text{EITHER } e1 \text{ THEN } S1$		$(E=e1 \Rightarrow [S1]P) \wedge$
$\text{OR } e2 \text{ THEN } S2$		$(E=e2 \Rightarrow [S2]P) \wedge$
$\text{OR } \dots$	\equiv	\dots
$\text{OR } en \text{ THEN } Sn$		$(E=en \Rightarrow [Sn]P) \wedge$
$\text{ELSE } T$		$(E \neq e1 \wedge \dots E \neq en \Rightarrow$
$\text{END}] P$		$[T]P)$



Need for consistent specifications

- Software development using B is based on mathematical (logical) proof
- In logics,
 $\text{false} \Rightarrow \text{any_statement}$
i.e. anything can be proved from false assumptions
- Analogously, an inconsistent (contradictory) specification can be implemented by any program
- To prevent this, B Method forces us to check consistency of an initial specification



Machine consistency conditions

- To check machine consistency, B generates four sets of proof obligations:
 - Constraint POs – to check that sets and constants given as machine parameters exist
 - Context POs – to check that local sets and constants satisfying given properties exist
 - Initialisation POs – to prove that initialisation assignment establishes a state satisfying the machine invariant
 - Operation POs (for each operation) – to prove that the operations maintain (preserve) the invariant.



Inconsistency of operations

Operations can be inconsistent because

- Operation precondition is too weak
- Operation body is not correct
- Invariant is too strong
- Invariant is too weak
- Invariant is simply wrong



Full machine consistency

Consistency conditions for a machine

```
MACHINE M(p)
CONSTRAINTS C
SETS St
CONSTANTS k
PROPERTIES B
VARIABLES v
INVARIANT I
INITIALISATION T
OPERATIONS
  y ← op(x) =
    PRE P
    THEN S
    END;
...
END
```



Full machine consistency (cont.)

- Consistency of constraints C :

$$\exists p \bullet C$$

- Consistency of properties B :

$$C \Rightarrow \exists St, k \bullet B$$

- Consistency of invariant I :

$$C \wedge B \Rightarrow \exists v \bullet I$$

- Consistency of initialisation T :

$$C \wedge B \Rightarrow [T] I$$

- Consistency of operations:

$$C \wedge B \wedge P \wedge I \Rightarrow [S] I$$

